REGULAR ARTICLE

Mean-field cooperativity in chemical kinetics

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Abstract We consider cooperative reactions and we
study the effects of the interaction strength among the
system components on the reaction rate, hence realizing a
connection between microscopic and macroscopic observables.
Our approach is based on statistical mechanics
models and it is developed analytically via mean-field
techniques. First of all, we show that, when the coupling
strength is set positive, a cooperative behavior naturally
emerges from the model; in particular, by means of various
cooperative measures previously introduced, we highlight
how the degree of cooperativity depends on the interaction
strength among components. Furthermore, we introduce a
criterion to discriminate between weak and strong cooperativity,
based on a measure of "susceptibility." We also
properly extend the model in order to account for multiple
attachments phenomena: this is realized by incorporating
within the model p-body interactions, whose non-trivial
cooperative capability is investigated too.

Keywords Michaelis–Menten · Hill · Binding isotherm ·
Statistical mechanics · Ising model · Reaction-kinetics

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1 Introduction

The phenomenon of cooperativity is widespread in biological
and chemical sciences and it has been the focus of many
theoretical and experimental investigations [1]. Cooperativity
is a typical "emergent" property that directly links the
description of a system at the single molecular, elementary
level, with the macroscopic properties in complex macromolecules,
cells, and organisms. It is often a compelling task
to exploit cooperative effects, such as amplification regimes
and high sensitivity to external parameters [2, 3].

A common feature of cooperative systems is the interaction
among "active sites." This interaction can result, for
example, in an increasing affinity for binding of substrate
as more sites are occupied, referred to as positive cooperativity
for binding. Conversely, if successive binding of
substrate to active sites reduces the binding affinity and
inhibits the occupation capability of another site, we speak
of negative cooperativity for binding.

Here we focus on the effects of cooperation on reaction
rate curves: when measuring the progress of a reaction as a
function of the concentration of substrate (e.g., the saturation
of hemoglobin by oxygen) [4, 5] one finds that
cooperation is typically associated with sigmoidal curves,
in contrast with the hyperbolic Michaelis–Menten law [6],
holding when cooperativity is absent. Actually, the plethora
of different phenomena where cooperativity effects
have been observed in reaction rates is so spread that many
different definitions have been suggested in the past, most
of them being based on the measure of some kind of
deviations from the classical Michaelis–Menten reaction
kinetics [6]. While non-cooperativity is a well-defined
behavior in complex multi-sites binding, all the definitions
of cooperativity still lack a unifying picture, despite sharing
a common underlying mechanism.

Here our aim is to suggest a unifying picture for cooperative behavior in multi-sites systems. Our approach is based on statistical mechanics and on an effective microscopic description, able to emphasize the role of interactions between sites and to recover all the different behaviors and definitions at the macroscopic level.

A first step in this direction has been paved [7] by using linear spin chains for modeling nearest-neighbors correlations among sites associated with two-values variables and indicating the binding/non-binding state; here we move forward, by assuming a simple mean-field interaction structure among active sites as this allows to understand and classify complex behaviors of macromolecules. More precisely, minimizing a suitably introduced free energy we obtain an explicit expression of the reaction rate as a function of substrate concentration and of a possible coupling among binding sites. In particular, we show that the strength of the interaction among active sites discriminates in a simple way between Michaelis–Menten curves and cooperative behavior, the latter in agreement with several, well-known criteria (e.g., Hill, Koshland, range, etc.); furthermore, we identify a critical interaction threshold where strong cooperativity sets in/out, also showing that a sigmoidal rate law is not necessary for cooperativity. In our framework, also reaction rates curves with an almost discontinuous step in a defined range of concentration can be recovered. In particular, the behavior of the reaction curves around the discontinuous step can be given by an interesting representation in terms of "critical" parameters. Finally, by extending our model to multi-sites attachment (a reasonable assumption when binding occurs on macromolecules or on a homogeneous surface), we obtain reactions curves exhibiting different features (weak, strong, sigmoidal, or discontinuous step), as observed experimentally [4], and negative cooperativity may naturally arise.

The main point in our analysis is the effective microscopic description, typical of statistical mechanics and allowing for a clear interpretation of different macroscopic cooperative behaviors. The general interaction parameter we introduce is certainly not sufficient to reproduce correctly the complex mechanisms acting at the elementary level, but its effective value encodes some of the most relevant features observed in reactions curves. That is to say, from different observed shapes in reaction curves we can infer the effective microscopic structure of interactions between active sites. In our framework, Hill coefficients and cooperativity measures can be given an elementary interpretation and the comparison between systems associated with different cooperativity values can be translated in a relation between their structural properties.

The paper is organized as follows: In Sect. 2 we briefly summarize the principal definitions of cooperativity in chemical kinetics, and in Sect. 3 we introduce our statistical mechanics framework. The latter is then thoroughly investigated as explained in Sect. 4, where we also recover previous definitions of cooperativity. In Sect. 5 we properly extend our model in order to account for multi-attachment too. Outlooks and conclusions then follow.

2 Measures of cooperativity

In elementary chemistry, cooperativity can be defined as the ability of ligand binding at one site on a macromolecule to influence ligand binding at a different site on the same macromolecule; according to whether the affinity of the binding sites for a ligand is increased or decreased upon the occupation of a neighboring site, we speak of positive or negative cooperativity, respectively. A common example is provided by hemoglobin, which displays four binding sites whose affinity for oxygen is increased when the first oxygen molecule binds [7].

In order to study the existence and the extent of cooperativity, a convenient observable is the fractional saturation of binding sites at equilibrium θ (θ = occupied sites/total sites) for different values of free ligand concentration α.[1] Due to the number of possible forms and levels of cooperativity, a multitude of diagnostic tests have been introduced in literature (see for instance [6]), mainly based on the comparison to a non-cooperative behavior. The latter occurs when the binding sites act independently and are identical in their activity; this behavior is observed for example in myoglobin in the presence of oxygen [7]. In such cases, the equilibrium reaction curve is well defined and exhibits the familiar hyperbolic Michaelis–Menten (MM) form

$$\theta_M(\alpha) = \frac{\alpha}{\alpha + K_M}, \tag{1}$$

where K_M, called the MM constant, rules the affinity between components, and α accounts for the substrate concentration; note that θ_M correctly saturates to 1 [1]. Hence, cooperativity is expected to be at work when the reaction rate does not follow MM kinetics.

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[1] In chemical kinetics, one is typically interested in finding the rate law governing a reaction, i.e., how the concentration of a given reactant or product varies in time. For elementary reactions (i.e., reactions with a single mechanistic step) the law of mass action is valid, and the reaction rate is proportional to reactant concentrations raised to a power defined by stoichiometric coefficients, but this is no longer true for complex reactions. However, if the substrate molecules react on binding sites to form a product, as is the case of enzymes, we expect the rate for product formation to be still proportional to the fraction of occupied sites θ.

We now review different measures and, accordingly, definitions of cooperativity (see also [6, 8, 9]), neglecting those (e.g., Wong co-operativity [10]), which are restricted to particular forms for the reaction rates. We also omit those based on the shape of $\theta(\alpha)$ for α close to zero, as this is not necessarily indicative of the behavior at intermediate substrate concentrations: Indeed, mixtures of positive and negative co-operativity, different degrees of co-operativity, and the occurrence of tipping points may not be predicted in this way.

2.1 Koshland cooperativity

The Koshland measure of cooperativity is one of the easiest to implement, being based on the coefficient κ, defined as the ratio

$$\kappa = \frac{\alpha_{0.9}}{\alpha_{0.1}}, \tag{2}$$

where $\alpha_{0.1}$ and $\alpha_{0.9}$ are defined as those values of ligand concentration such that $\theta(\alpha_{0.1}) = 0.1$ and, similarly, $\theta(\alpha_{0.9}) = 0.9$: For the MM hyperbolic function $\theta_M(\alpha)$, one would get $\kappa = 81$, independent of K_M. Hence, one can notice that if $\kappa < 81$ then $\theta(\alpha)$ is expected to grow faster than $\theta_M(\alpha)$ and, according to Koshland, we speak of positive cooperativity, while if $\kappa > 81$, then we have negative cooperativity.

The index κ has the advantage of being an absolute number, but the disadvantage of being sensitive to the scale of measurements and of depending only on $\alpha_{0.1}$ and on $\alpha_{0.9}$, hence ignoring all information that can be derived from the shape of $\theta(\alpha)$.

2.2 Global dissociation quotient

Another possible approach to measure the degree of cooperativity is in terms of deviations from the hyperbolic behavior by introducing the generalized equation [11]

$$\theta(\alpha) = \frac{\alpha}{\alpha + K(\alpha)}. \tag{3}$$

In the absence of cooperativity $K(\alpha)$ is constant, viceversa one gets $K(\alpha) = \alpha(1 - \theta)/\theta$. Hence, the experimental value of $K(\alpha)$ can be interpreted as the ratio between free sites and occupied sites times α and it is often called "global dissociation quotient." The slope of this curve, symbolized by γ, i.e., $\gamma = dK(\alpha)/d\alpha$, is used as a quantitative measure of cooperativity: γ equal, greater or smaller than zero would correspond to absence of cooperativity, negative and positive cooperativity, respectively. Under this view, the phenomenon of cooperativity is equivalent to the change in the global dissociation quotient with ligand concentration; the larger the rate of change of $K(\alpha)$ and the larger the degree of cooperativity.

2.3 Hill cooperativity

An alternative way to quantify the deviation from an hyperbolic behavior is to use the so-called Hill function, which provides another extension of the MM function and which reads

$$\theta_H(\alpha) = \frac{\alpha^h}{\alpha^h + K_M}, \tag{4}$$

with K_M and h constant. Indeed, Eq. (4) is able to successfully fit most experimental data from cooperative systems, where the parameter h can be interpreted as the number of ligand molecules that bind to the macromolecule in a single step [12].

More generally, given experimental data for $\theta(\alpha)$, one can define the Hill coefficient as

$$n_H(\alpha) = \frac{d\left[\log\frac{\theta(\alpha)}{1-\theta(\alpha)}\right]}{d(\log\alpha)} = \alpha\frac{d\left[\log\frac{\theta(\alpha)}{1-\theta(\alpha)}\right]}{d\alpha}, \tag{5}$$

which provides a measure of the extent of cooperativity: when $n_H(\alpha) > 1$ for all $\alpha > 0$, we have positive cooperation; viceversa, if $n_H(\alpha) \leq 1$ for all $\alpha > 0$ we have negative cooperation. For instance, for oxygen binding to hemoglobin (with $N = 4$ binding sites), the estimated Hill coefficient is about 2.8. Indeed, in biochemical processes n_H is typically smaller than N, suggesting a mixed effect resulting from the interaction among sites [4].

It is worth noticing that the main difference between γ and n_H is that the former represents the absolute change in global dissociation quotient per absolute change in ligand concentration, while the latter is related to the corresponding logarithmic changes. However, notice that both assume an a priori rate function to be compared with experimental data.

Finally, we underline that, given the experimental curve $\theta(\alpha)$, one can straightforwardly get an estimate for n_H, and this explains the popularity of such cooperativity measure; nonetheless, n_H constitutes a macroscopic property and it is not uniquely related to the difference in binding affinity due to the occupancy of next sites, which, conversely, is a microscopic property.

2.4 Range cooperativity: weak or strong behavior

The range measure is, again, based on a comparison between the reaction curve $\theta(\alpha)$ and an "appropriate" hyperbolic MM curve, as summarized in the following (see also [6]): first, one specifies a value $K > 0$ and builds the hyperbolic function $\theta_K(\alpha) = \alpha/(\alpha + K)$. Then, if $\theta'(0) < \theta'_K(0)$ ($\theta'(0) > \theta'_K(0)$) and $\theta(\alpha)$ and $\theta_K(\alpha)$ intersect at most once for all choices of $K > 0$, we say that $\theta(\alpha)$ is *strongly* positive (negative) cooperative. If $\theta(\alpha)$ and $\theta_K(\alpha)$ intersect

more than once, it is possible to formulate a concept of *weak* cooperativity (in the range sense): If $\theta'(0) < \theta'_K(0)$ $(\theta'(0) > \theta'_K(0))$ and $\theta(\alpha) > \theta_K(\alpha)$ $(\theta(\alpha) < \theta_K(\alpha))$ for large enough α, then $\theta(\alpha)$ is weakly positive (negative) cooperative.

As proved in Karlin [6], for monotone increasing rate curves the range and Hill measures of cooperativity are equivalent, more precisely, strong positive (negative) cooperativity with respect to the range measure is equivalent to a positive (negative) cooperativity according to Hill. However, differently from Hill measure, which requires the estimate of the slope for $\log \theta(\alpha)$ against $\log \alpha$, range measurements do not require interpolating data according to a given reaction rate and therefore the diagnosis of cooperativity is relatively simpler and also offers additional advantages [6]. In particular, the method is able to distinguish different degrees of cooperativity (weak and strong), even though such a distinction is still based on macroscopic evidences and cannot be directly ascribed to specific values or range of values in the microscopic parameters characterizing the phenomenon.

3 Bridging chemical kinetics and statistical mechanics

Let us consider a system which has a set of N interacting binding sites, numbered by an index $i = 1, 2, \ldots, N$. Each site can bind one identical smaller molecule of a substrate, and we call α the concentration of free substrate molecules. When a site has a molecule bound on it, binding on all the other sites is enhanced (inhibited), which corresponds to a system with positive (negative) cooperativity. This is the case, for instance, of homo-allosteric enzymes, or some catalyst surfaces [13, 14]. Even small monomeric systems, such as small signaling proteins (Chemotaxis protein Y) or small ribozymes, may have a similar behavior [15].

In analogy with the Ising model (see for instance [7]), we associate in complete generality to each binding site a dichotomic variable σ_i which takes the value $+1$ if the ith site is occupied, and -1 if it is unoccupied. A configuration of the molecule is then specified by the set of values $\sigma_1, \sigma_2, \ldots, \sigma_N = \{\sigma\}$.

Once this bridge has been established, we can speculate on the way the binding sites interact with the substrate and/or among themselves. Now, such interactions are based on electromagnetic exchange forces so that the third law of dynamics holds, hence, the intrinsic symmetry of the exchanges implies symmetry in the couplings which ensures detailed balance, which, in turn, ensures the equilibrium canonical framework to hold and, ultimately, an Hamiltonian representation of the phenomenon. In this way, we can apply the standard statistical mechanics machinery and the equilibrium state for the system

corresponds to the minimum energy and the maximum entropy. As a result, when the system is in equilibrium with a heat bath at a given temperature T, the probability of a configuration with energy H_N is proportional to the Boltzmann factor $\exp(-H_N/k_B T)$, where k_B is the Boltzmann constant and T is the temperature or, more generally, the level of "noise" experienced by the system.

We first focus on the interaction between the substrate and the binding site which is expected to depend on both the substrate concentration and on the state of the binding site; we model such interaction by an "external field" h meant as a proper measure for the concentration of free ligand molecules. Then, for a non-interacing model (whose potential cooperation features are obviously neglected) one can consider a microscopic interaction energy given by

$$H_N(\{\sigma\}; h) = -h \sum_{i=1}^{N} \sigma_i. \tag{6}$$

We can think at h as the chemical potential for the binding of substrate molecules on sites: When it is positive, molecules tend to bind to diminish energy, while when it is negative, bound molecules tend to leave occupied sites. If we assume that the free molecules are non-interacting (which is reasonable when they are very diluted), the chemical potential can be expressed as the logarithm of the concentration of binding molecules and one can assume that the concentration is proportional to the ratio of the probabilities of having a site occupied with respect to that of having it empty [7]. In this simple case, being the sites non-interacting, the probability of each configuration is the product of the single independent probabilities of each site to be occupied and one finds $\alpha \propto p(\sigma_i = +1)/p(\sigma_i = -1) = \exp(+h)/\exp(-h)$, so that

$$h = \frac{1}{2}\log \alpha. \tag{7}$$

Hence the limit $h \to -\infty$ corresponds to a vanishing concentration α, while when $h \to +\infty$ the concentration α goes to infinity as well. It is straightforward to see that the reaction rate associated with Eq. (6) recovers to the hyperbolic Michaelis–Menten curve [7].

Once we have successfully tested the statistical mechanics approach for the paradigmatic MM kinetics, we can proceed with our mapping and account for cooperativity just by extending the one-body theory previously outlined: To model the interaction between sites, we simply introduce the full Curie–Weiss (CW) Hamiltonian [16]

$$H_N(\{\sigma\}; J, h) = -\frac{J}{2N} \sum_{i \neq j}^{1,N} \sigma_i \sigma_j - h \sum_{i=1}^{N} \sigma_i, \tag{8}$$

which, again, represents the microscopic energy of the system in a given configuration, so that the lower H_N and

the larger the probability of finding that configuration. Of course, $J > 0$ means that there exists a two-body interaction between the binding sites, and the free energy is better minimized if sites "cooperate" by aligning consistently.

The Hamiltonian (Eq. 8) was originally introduced to describe a system of atoms with magnetic moments: the spins σ's can point in two possible directions, h represents an homogeneous external magnetic field acting on each atom and spanning all real numbers, and J is a fixed number representing the two-bodies interaction strength (the exchange term), which for our model rules the cooperativity of the system. In fact, the first term in Eq. (8) is an interaction between the $N(N-1)/2$ couples of sites: if J is positive, this energy is smaller the larger the alignment displayed by the σ's. In the following, we focus on positive couplings $J_{ij} > 0$. The first term ranges from its minimum value $-J(N-1)/2$, obtained in the extreme cases in which all sites are either all occupied or all empty, to its maximum value 0, obtained at half saturation of the sites. So this contribution to the energy is such that sites tend to behave coherently, and the constant parameter J fixes the scale of the microscopic binding energy. Notice that the symmetry empty-occupied is actually broken in the presence of an external field, namely of a sufficiently large substrate concentration α which favors positive (occupied) states.

Before proceeding, we stress that our model corresponds to a so-called mean-field approximation, where each site interacts with all the remaining $N-1$ with the same strength J. Actually, this assumption may include several kinds of situation: systems where the motion of binding sites occurs on time-scales short enough for them to see each other before reacting, or the binding of molecules to semiflexible polymers in the limit of long-range interactions [17].

We also underline that a stochastic approach like ours is meaningful only if the number of elements taken into account is large; in particular, our solution holds rigorously in the thermodynamic limit (i.e., $N \rightarrow \infty$), nevertheless, the predictiveness of our model can be significant even for a finite-size folded macromolecule, built up by, say, $N \sim 1,000$ binding sites, provided that the physical/chemical features are retained under scaling, namely, we need to assume that the number of neighbors for any site scales with N. This is indeed consistent with the mean-field approach and ensures that the statistical overlap between global and local behavior is strong in the large N limit. Otherwise stated, the features of an infinite length molecule, whose interaction are properly rescaled within a mean-field approach, can be still comparable with a realistic one.

Furthermore, despite its simplicity, the model displays a rich phenomenology: by tuning the ratio J/T, the model gives rise to different behaviors and degrees of cooperativity;

it is also mathematically tractable and it accounts for a discontinuous rate law which linear models with nearest-neighbors interactions cannot recover. In such discontinuous regime, i.e., close to criticality, its predictions (which are unsensitive to the underlying topology) may barely represent the real phenomenon, quantitatively. However, as we will see, they can suggest an interesting measure to be performed on nearly discontinuous regimes.

The model could be further extended by including, for instance, a given topology for binding sites [18, 19], in such a way that the effective number of neighbors per site is smaller than N (and may even remain finite in the thermodynamic limit), or a coupling J_{ij} depending on the couple of sites considered, say, scaling with their distance; the resulting mathematics would be more complicated, without any real qualitative change. Thus, keeping the framework as simple as possible for the sake of clearness, we introduce the standard statistical mechanics definitions for the CW model. The normalized probability for a configuration $\{\sigma\}$ is then

$$P_N(\{\sigma\}; J, h, T) = Z_N^{-1} \exp(-H_N(\{\sigma\}; J, h)/k_B T), \qquad (9)$$

where the normalizing factor $Z_N(J, h, T) = \sum_{\{\sigma\}} \exp(-H(\{\sigma\}; J, h)/k_B T)$ is termed the partition function. The number $n\{\sigma\}$ of occupied sites can be computed as

$$n\{\sigma\} = \sum_{i=1}^{N} \frac{1}{2}(1 + \sigma_i), \qquad (10)$$

and the binding isotherm $\theta(\alpha)$ is reconstructed from the average fraction of occupied sites $\langle n \rangle/N$ as a function of the concentration α

$$\theta = \frac{\langle n \rangle}{N} = \frac{1}{N} \sum_{\{\sigma\}} n\{\sigma\} P\{\sigma\} = \frac{1}{2} + \frac{1}{2} m(J, h), \qquad (11)$$

where $m(J, h) = \sum_i \langle \sigma_i \rangle/N$ represents the average magnetization per site in mean-field CW model, the brackets $\langle . \rangle$ account for the Boltzmann average (i.e., $\langle . \rangle = \sum_\sigma . \exp(-\beta H_N)/Z_N$); the dependence on α is obtained simply by replacing h with $(1/2) \log \alpha$ (see Eq. 7). Here m represents the average fraction of occupied (or unoccupied) sites with respect to half saturation. In the limit of large N, the average value $\langle n \rangle/N$ can be obtained by minimizing, with respect to the parameter $\theta \in (0,1)$, the effective free energy [16]

$$F(\theta, \alpha, T) = \sup_{|\theta|} \left(-\frac{J}{2}(2\theta - 1)^2 - \frac{1}{2}(1 - \theta) \log(\alpha) - Ts(\theta) \right). \qquad (12)$$

The (only direct) independence of this variational prescription by the coupling constant (as the sup is taken just on θ) is the main strand we pave to obtain a unifying

picture of the various catalogs of cooperativity in chemical kinetics: It holds whatever J.

The first two terms at the r.h.s. of Eq. (12) stand for the internal energy, which corresponds to the Boltzmann average of the Hamiltonian $H(\{\sigma\}, J, h)$ expressed as a function of θ and α, while

$$s(\theta) = -\theta \log(\theta) - (1 - \theta) \log(1 - \theta) \qquad (13)$$

is the entropic term, whose weight is ruled by the temperature T. For small temperatures, the most likely configurations are those associated with small values of the internal energy; for large temperatures the most likely configurations are those corresponding to higher values of entropy.[2] Therefore, the minimum of F is the optimal compromise between the minimization of the effective internal energy and the maximization of entropy. We expect that for large interactions J (or chemical potentials) the energy term in Eq. (12) is the leading contribution, and the optimal fraction is ruled by this term, so that the sites tend to be in the same state and the binding isotherm displays a sigmoidal shape, while for small values of the interaction strength the leading term will be the entropic one, which at a fixed value of the chemical potential prefers disordered states, i.e., states obtained by a large number of configurations, and pushes the rate law toward a MM form: In this sense the temperature can be thought of as a noise because when it is high the system prefers to be in a disordered state. However, large or small temperatures are defined with respect to the interaction strength J and in the following we are going to fix the temperature equal to 1 and let the interaction strength vary to see all the possible regimes of binding isotherms arising from different values of J, as the latter rules cooperativity.

The minimum condition for Eq. (12) with respect to the order parameter θ corresponds to the CW self-consistence equation [16, 20]

$$\theta(J, \alpha) - \frac{1}{2} = \frac{1}{2} \tanh\left(J(2\theta - 1) + \frac{1}{2}\log(\alpha)\right) \qquad (14)$$

and gives the average fraction of occupied sites corresponding to the equilibrium state for the system. From more general perspective, the model introduced here can also be looked at as statistical mechanics version of the so-called concerted model or Monod–Wyman–Changeux (MWC) model [21]. The basic idea of such a model is that regulated proteins (e.g., enzymes or receptors), in the absence of any regulator exist in different states, say two

reversible $\sigma_i = \pm 1$. The fraction of elements assuming a given state is determined by thermal equilibrium. In the presence of regulators (e.g., a substrate α) one state may prevail against the other.

As we will see later, Eq. (14) describes a second-order phase transition when $\alpha = 1$ and J larger than the critical value $J_c = 1$. Conversely, when $J > J_c$ and $\alpha = \alpha_c = 1$, the transition is first order and the average fraction θ has a discontinuity. Equation (14) holds rigorously just in the thermodynamical limit ($N \to \infty$); for finite systems, beyond $\mathcal{O}(1/N)$ corrections (see for instance [16]), we recall that the discontinuous functions are mildly smoother, accordingly with the experimental counterparts [1].

4 Obtaining chemical kinetics from statistical mechanics

As discussed in the introduction, to determine the rate law one has to compute the average fraction of occupied sites as a function of the concentration of free ligand molecules α, and this dependence is encoded in the self-consistence Eq. (14).

We consider separately the two cases $0 \leq J < 1$ and $J > 1$ for the interactions between sites, because, as stated, while in the former case θ is everywhere continuous in α, in the latter it has a discontinuity in $\alpha = 1$, taking a value smaller than 1/2 when $\alpha \to 1^-$ and greater than 1/2 when $\alpha \to 1^+$. In both cases, however, it is easy to check that $\theta(\alpha) \to 0$ for $\alpha \to 0$ (which corresponds to the $h \to -\infty$ limit) and $\theta(\alpha) \to 1$ for $\alpha \to \infty$ ($h \to +\infty$). This means that the reaction rate vanishes when the substrate concentration vanishes and it saturates to one when the substrate concentration is large, as expected.

When $J \to 0$, no cooperativity is expected (as the model reduces to a one-body theory) and, coherently, we recover the MM kinetics. In fact, the rate Eq. (14) can be equivalently expressed as

$$\theta(\alpha, J) = \frac{\alpha \exp[2J(2\theta(\alpha, J) - 1)]}{1 + \alpha \exp[2J(2\theta(\alpha, J) - 1)]} \qquad (15)$$

which properly gives, for $J = 0$

$$\theta(\alpha, J)|_{J=0} = \frac{\alpha}{1 + \alpha}. \qquad (16)$$

Note that we do not lose generality when obtaining $\alpha/(1 + \alpha)$ instead of $\alpha/(K + \alpha)$ at the r.h.s. of Eq. (16): in fact, we can rewrite the MM equation as $\theta(\alpha) = K_M^{-1}\alpha/(1 + K_M^{-1}\alpha)$ such that choosing $K_M \neq 1$ is equivalent to shifting $\alpha \to \alpha/K_M$, which can be compensated by shifting $h \to (1/2)\log \alpha - (1/2)\log K_M$ as well.

Moreover, from Eq. (15), we get that when $J > 0$ the rate for a given concentration is smaller than the

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[2] We notice that the entropic term is connected to the logarithm of the number of configurations associated with a given fraction θ of occupied sites: It is maximized for fractions around 1/2, which have a larger number of configurations associated, and minimized for $\theta = 0$, $\theta = 1$, corresponding to just one configuration and a vanishing entropy.
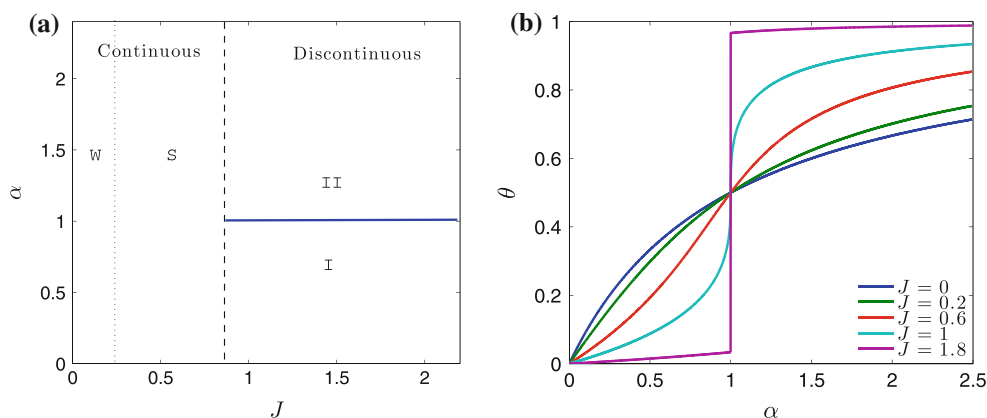
Fig. 1 Phases and binding isotherms. **a** The figure shows the different phases for the system. For $J < 1/4$ the binding isotherms have no inflection point and the system is weakly (W) cooperative; when $1/4 < J < 1$ an inflection point arises, and the presence of a sigmoidal shape allows us to call this regime strongly (S) cooperative; both regions correspond to a continuous varying $\theta(\alpha)$, while for $J > 1$ $\theta(\alpha)$ becomes discontinuous, with a jump at the critical concentration $\alpha = 1$ (*blue line*). **b** Different regimes for the binding isotherm obtained by varying the interaction strength J. For $J = 0$ (*blue line*) the hyperbolic Michaelis–Menten law represents the isotherm for a non-interacting system; for $J = 0.2$ (*green*) the system is in a weakly cooperative regime; for $J = 0.6$ (*red*) strong cooperativity manifests itself with the typical sigmoidal shape; $J = 1$ (*light green*) is the critical regime: the derivative in the inflection point which gives the Hill coefficient is infinite; $J = 1.8$ (*purple*) represents the discontinuous phase, with an extremely strong cooperativity

corresponding one for a non-interacting system when $\alpha < 1$, and becomes greater when $\alpha > 1$; in fact, the greater the interaction and the steeper the sigmoidal shape of the rate. Equation 15 is plotted in Fig. 1 versus α and for several values of J.

Interestingly, a global change in the system considered, e.g., concerning ph or temperature, may lead to variations in the affinity between binding site and reactants as well as in the coupling strength between binding sites themselves, giving rise to a curve $\theta(\alpha)$ displaying a different steepness; the Bohr effect is one of the best-known manifestations of these phenomena [22].

Now, the derivative[3] of θ with respect to α, which is strictly related to the Hill coefficient and, consequently, to the cooperativity of the system, can be computed from Eq. (14):

$$\frac{\partial \theta}{\partial \alpha} = \frac{1}{4\alpha} \frac{1 - (2\theta - 1)^2}{1 - J\left[1 - (2\theta - 1)^2\right]}. \tag{17}$$

It is always positive and finite for $J < 1$, meaning that θ is an increasing function of α, as we expect. In the limit of low concentration we obtain

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[3] Note that in the frame of the Curie–Weiss model this is strictly related to the generalized susceptibility

$$\chi = \frac{\partial m(h)}{\partial h}$$

which measures the response of the system to a change in the field h. In fact, we have

$$\frac{\partial \theta}{\partial \alpha} = \frac{1}{2} \frac{\partial m(h(\alpha))}{\partial \alpha} = \frac{1}{2} \frac{\partial h}{\partial \alpha} \chi(h(\alpha)) = \frac{1}{4\alpha} \chi(h(\alpha)).$$

$$\left.\frac{\partial \theta}{\partial \alpha}\right|_{\alpha=0} = \exp(-2J) \tag{18}$$

and the kinetics at very low concentration is governed by the two-bodies interaction J: the greater J and the flatter the rate law. Note that the strength of the cooperativity, J, appears in Eq. (18) as an exponent, implicitly supporting the log-scale of the Hill coefficient in Eq. (5). When $J = 0$, $\partial_\alpha \theta|_{\alpha=0} = 1$ and one properly recovers the same trend as that of the MM kinetics, which has a first-order kinetics with the same coefficient for small concentrations.

Finally, to recognize the sigmoidal shape typical of cooperative systems, we have to study the second derivative, which can be easily computed and expressed in terms of the first one:

$$\frac{\partial^2 \theta}{\partial \alpha^2} = -\frac{1}{\alpha} \frac{\partial \theta}{\partial \alpha} \left[1 + \frac{2\theta - 1}{\left(1 - J\left[1 - (2\theta - 1)^2\right]\right)^2} \right]. \tag{19}$$

When α ranges in $(1, \infty)$, this is always negative, so that θ is a concave function of α in that range, for any value of J. For $\alpha = 1$ we have $\partial^2_{\alpha^2}\theta = -(1/4)/(1 - J)$, so that θ is still concave there. For $\alpha \in (0,1)$ a numerical study of the second derivative clearly shows that there are different behaviors, depending on J.

4.1 $J < 1/4$: weak cooperativity

Interestingly, an inflection point is absent not only for $J = 0$, but even for greater values, namely $J \leq 1/4$. In fact, expanding θ to the first order in α one finds

$$\left.\frac{\partial^2 \theta}{\partial \alpha^2}\right|_{\alpha=0} = -2(1 - 4J)\exp(-4J) \quad (20)$$

so in this interval the rate function θ is everywhere concave, tending, for $J \to 0$, to the hyperbolic MM form (whose second derivative $-2(1 + \alpha)^{-3}$ is always negative). Note that when $J = 0$ the expression (20) gives, correctly, the MM value -2. The absence of an inflection point in the region $J \in [0, 1/4]$ allows us to define it as a weak cooperativity region: the shape of the binding isotherm is practically indistinguishable from that of a non-cooperative system.

4.2 $1/4 < J < 1$: strong cooperativity

The analysis of Eq. 19 also allows to derive that when $1/4 < J < 1$, there is a unique inflection point α^* (whose value increases with J), which separates the region where θ is convex (small concentration), to the one where it is concave. For $J = 1/4$ this point corresponds to $\alpha^* = 0$, while it is shifted toward unitary concentrations when J is close to 1. As a sigmoidal rate has necessarily an inflection point, we may talk about strong cooperativity in this interval, in contrast to the weak cooperativity previously introduced. These very simple definitions have the advantage of being directly related to the effective microscopic interaction, so that the experimental behavior of a system could allow one to reconstruct this interaction strength and interpret the rate law in terms of the very general mean-field model. The different phases for the binding isotherm are shown in Fig. 1.

4.3 $J > 1$: discontinuous rate law

We saw that when $J < 1$ we can consider two regions, a weak cooperative one, where the rate law is hyperbolic, and a strong cooperative one, with an inflection point growing gradually with the interaction strength.

When $J > 1$ (corresponding in the original Ising model to the "ferromagnetic" phase) the rate law is still increasing with α, and the expressions (18–20) remain valid for $\alpha \neq 1$. In this point the rate function is discontinuous and the jump is given by $\theta_+(J) - \theta_-(J)$, where

$$\theta_\pm(J) = \lim_{\alpha \to 1^\pm} \theta(\alpha, J).$$

These two limits depend on J: they are both equal to 1/2 for $J = 1$, when the curve is still continuous, and their difference increases smoothly with the square root of $J - 1$ when $J > 1$ (see Fig. 1). This means that, starting from vanishing concentration, the system has less sites occupied, for a given α, than the corresponding non-interacting one, until the concentration reaches the reference value. Here, it is sufficient to increase infinitesimally the number of free

molecules to obtain a large filling (depending on J). After that value, the number of occupied sites is always greater than the corresponding value for MM. Note that, in principle, if the concentration varies slowly one could observe metastability, with a curve which continues growing continuously up to values of $\alpha > 1$. The entire out of equilibrium features of the model are ruled out in this treatment as we deal with equilibrium statistical mechanics, however—as a second step—the bridge could be extended in that direction. If $J \to \infty$ this discontinuity increases, while its derivative in zero vanishes, so that in the large volume limit we obtain a step function. This corresponds to a chemical kinetics where no binding site is occupied until the concentration has reached the critical value $\alpha = 1$, and when this value has been reached all sites are occupied. This kind of discontinuous behavior can be observed, for example, in the binding isotherms of small surfactants onto a polymer gel [23].

When $J \to 1$ a second-order phase transition appears. This indicates that the correlation between binding sites becomes stronger and the typical trend of thermodynamical observables is a power law [16]. If the statistical mechanics picture we suggest applies to the reaction rates, then this power-law behavior becomes very interesting, as it should be related, as in the statistical mechanics counterpart, to very general features the systems, due to the concept of universality [16]. Let us consider in detail the behavior for $J \to 1$. As we said before, the discontinuity for $J > 1$ is given by $\theta_+(J) - \theta_-(J)$, whose dependence from J near the critical point ($\alpha = 1$, $J = 1$) can be expressed as

$$\theta_+(J) - \theta_-(J) \approx (J - 1)^{1/2}$$

while on the critical isotherm (i.e., for $J = 1$) around the critical concentration $\alpha = 1$, mean-field theory predicts

$$\theta(\alpha, 1) - \frac{1}{2} \approx (\alpha - 1)^{1/3}.$$

In this regime one can also predict the behavior of the α dependence of the Hill coefficient defined in Eq. (5), which, when $\alpha \to 1$, diverges as

$$n_H(\alpha) \approx (\alpha - 1)^{-2/3}.$$

Moreover, we know that when $J \to 1^\pm$ the susceptibility, and so the derivative of θ respect to α, diverges as

$$\chi|_{\alpha=1} \approx |1 - J|^{-1}.$$

As hinted in Sect. 3, the exponents of these power laws are only valid in the limiting case of a very large number of interacting neighbors per site, while for finite-size systems corrections depending on the real dimension of the space in which they are embedded are expected. However, these scalings, in particular those related to the reaction rate

around the discontinuity as a function of α, suggest a new interpretation of almost discontinuous reaction curves and could represent an interesting measurements to test our predictions. Indeed, statistical mechanics suggests that power-law behaviors in the vicinity of the discontinuous step are signatures of a critical phenomena: If in particular the detected exponents do not differ that much from the ones predicted by the CW model, then this suggests that the mean-field picture, despite its simplicity, is able to capture the essence of the cooperative phenomenon.

4.4 Cooperativity through the Hill coefficient

As explained in Sect. 2, the usual way to define in a quantitative manner the cooperativity of a system is by the Hill coefficient, i.e., the slope at the symmetric[4] [1] point $\theta = 1/2$

$$n_H = \frac{1}{\theta(1-\theta)}\frac{\partial\theta}{\partial\log\alpha}\bigg|_{\theta=1/2} = 4\frac{\partial\theta}{\partial\log\alpha}\bigg|_{\theta=1/2} \qquad (22)$$

If binding on different sites is an independent process, one simply finds $n_H = 1$, while in the extremum case in which sites are either all empty or all occupied $n_H = N$. We call a system cooperative (non-cooperative) if $n_H > 1(n_H = 1)$, while the cooperativity is said to be negative, meaning that binding is reduced if there are occupied sites, for $n_H < 1$. So this gives a lower bound for the number of interacting sites, and it is possible to see that it is related to the variance of the mean number of occupied sites.

The Hill coefficient for our general model depends, as expected, on the interaction J; in particular for $J < 1$ we have

$$n_H \equiv \frac{\partial\log[\theta/(1-\theta)]}{\partial\log\alpha} = 4\frac{\partial\theta}{\partial\alpha}\bigg|_{\alpha=1} = 1/(1-J). \qquad (23)$$

Being the derivative of θ for $\alpha = 1$, the Hill coefficient is finite (and greater than one) for $J < 1$ and it diverges for $J \to 1^-$ when the discontinuity appears. An infinite Hill coefficient may seem unrealistic; however, it is not an unavoidable feature of our modeling: in fact, h scales with the connectivity of the underlying network of interactions and, while the latter diverges in this minimal fully connected representation, diluted mean fields can still work finely. However, as the mathematics involved becomes immediately very heavy we preferred to present the pure

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[4] When there is not such a symmetry, one should more properly consider the quantity

$$n_H = 4\frac{\partial\theta}{\partial\log\alpha}\bigg|_{max,min}. \qquad (21)$$

that is the slope of $\theta(\log\alpha)$ calculated at the inflection point, where it has an extremum. In fact for an unsymmetrical system the slope at $\theta = 1/2$ is not generally an extremum slope and should not be taken as a suitable cooperativity index.

theory within the limitation of the high connectivity limit. We observe that the last equation relates n_H to the typical scale of interaction energy. This is a macroscopic measure of cooperativity which is directly associated with the microscopic interactions among sites.

4.5 Cooperativity through the global dissociation quotient measure

Among the useful tools to describe cooperativity, we recall the global dissociation quotient $K(\alpha)$, whose derivative γ is expected to be different from zero when some form of cooperation occurs; in particular, γ should be negative when there is a positive cooperation. Figure 2 shows some plots of $\gamma(\alpha)$ for different values of J: consistently with the definition of $K(\alpha)$, (see 2), in the region of $\alpha < 1$, the stronger the interaction, the smaller γ, properly indicating the deviation from the K-constant MM curve. As the derivative of θ with respect to α appears in the definition of γ, in correspondence of the critical value $J = 1$, $\gamma(\alpha)$ diverges for $\alpha = 1$. In fact, this is the (critical) region where the correlations between sites, and so the cooperativity, are expected to diverge.

For sake of clarity in the figure, we did not show a plot of γ for $J > 1$; however, in this case the curve is below the others shown for $\alpha < 1$ and it is not defined for $\alpha = 1$: from this point on, it is practically vanishing.

4.6 Cooperativity through the Koshland measure

Lastly, we want to recover even the measure of cooperativity introduced by Koshland (see Sect. 2.1): To satisfy this task, we plotted the previously defined Koshland coefficient as a function of the two-bodies interaction coupling J (see Fig. 2), as the latter is the only relevant tunable parameter to explore cooperativity at work.

The coefficient is defined only for $J < 1.5$; in fact, for $J > 1$, $\theta(\alpha)$ is a discontinuous function and when $J \geq 1.5$ the equations $\theta(\alpha) = 0.1$ and $\theta(\alpha) = 0.9$ cease to have a solution.

As shown in Fig. 2 (bottom), we find that it is a decreasing function of J, which takes the value $\kappa = 81$ for non-interacting systems ($J = 0$), and $\kappa \sim 1$ when $J = 1.4$: Coherently with this scenario, we note that $\theta(\alpha = 1) = 1/2$ for every $J \leq 1$, when $J > 0$ the binding isotherm is below the MM isotherm for $\alpha < 1$ (such that $\alpha_{0.1}$ is larger than in MM theory) and above MM curve for $\alpha > 1$ (such that $\alpha_{0.9}$ is smaller than in MM theory).

5 Multiple interacting systems

When considering the binding of systems like long chain molecules, possibly on a homogeneous surface [24], it may
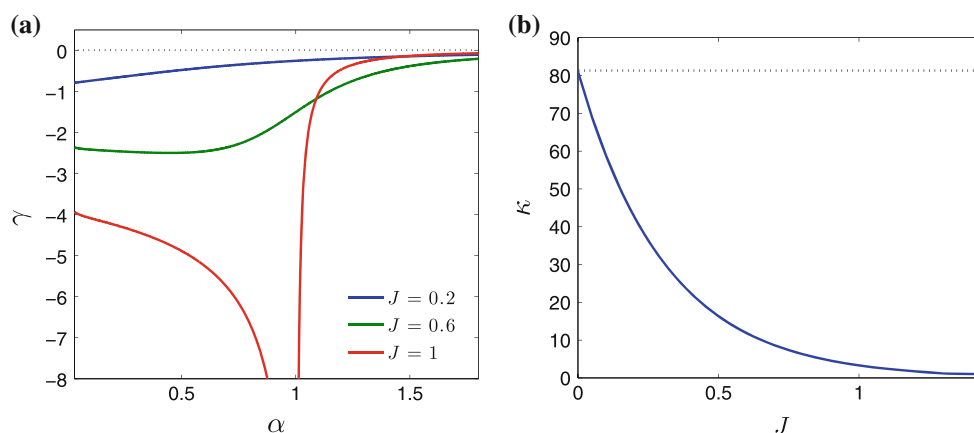
Fig. 2 Global dissociation quotient and Koshland coefficient. **a** The figure shows different regimes for the derivative of the global dissociation quotient $\gamma(\alpha) = dK/d\alpha$ obtained by varying the interaction strength J. For $J = 0.2$ (*green*) γ remains quite close to zero, indicating that K is nearly constant in α, as one expects for a non-cooperative system; for $J = 0.6$ (*red*) the global dissociation quotient has a stronger dependence on α: we know that in this case the binding isotherm has a sigmoidal shape and strong cooperativity appears; when $J = 1$ (*cyan*) we are in the critical regime, where the derivative of θ, and so γ, diverges at $\alpha = 1$. **b** The Koshland coefficient $\kappa = \alpha_{0.9}/\alpha_{0.1}$ obtained by our theory as a function of the two-bodies interaction J. It is a decreasing hyperbolic function, defined for values of J below $J = 1.5$, which tends to be lower when cooperatively is larger and the binding isotherm takes a steeper sigmoidal form. The dotted lines represent in both figures the reference values corresponding to a non-cooperative system, i.e., $J = 0$

be possible that the interaction involves more than two hosting sites per time and this can in principle affect the global "cooperative capability" of the system. Thus, in the following, we want to extend our model by accounting for multiple interactions, involving more than two elements together, in particular three- and four-bodies interactions.

The simplest p-body interaction among N sites which can be either occupied or empty ($\sigma_i = +1$ or -1, respectively) can be expressed by the Hamiltonian (Eq. 24)

$$H_N(\{\sigma\}, J, h) = -\sum_{p=2}^{\infty} \frac{p!}{2N^{p-1}} J_p \sum_{1 \leq i_1 < \cdots < i_p \leq N} \sigma_{i_1} \ldots \sigma_{i_N}$$
$$- h \sum_{i=1}^{N} \sigma_i. \tag{24}$$

The interaction strength J is assumed to be positive (for $J = 0$ we recover the standard MM kinetics again) and the combinatorial factor before the summation makes the energy extensive and accounts for a sensible $p \to \infty$ limit [25, 29].

It is easy to see that the energy (the mean value of the Hamiltonian) scales as

$$\langle H_N \rangle \propto N \langle m\Phi(m) \rangle, \quad \Phi(m) = \sum_{k=1}^{p-1} c_k m^k + h, \tag{25}$$

where c_k is the coefficient of the Taylor series implicitly defined by Eq. (25), and $m = 2\theta - 1$.

The argument in the self-consistent equation $m = \tanh(\Phi)$ is then built up, in complete generality, by all the

terms of the Taylor series (whose convergence is tackled by the $p!$ term in the numerator). However, as $|m| \leq 1$ we expect that only the first terms do matter in the thermal average and the main contribution is given by the term corresponding to $p = 2$, which has been studied in detail so far.

Let us highlight here another advantage in performing the statistical mechanics approach: As the Hamiltonian (Eq. 24) represents a sum of Hamiltonians (each for a different value of p), which, in principle, can have very different coupling strengths (i.e., the distribution of J_p can range over several orders of magnitude), in this case solving the global problem as a whole can be prohibitive, while here we can consider each Hamiltonian contribution by itself and focus only on one single term per time (namely $p = 2, 3, 4, \ldots$). This procedure, which we are going to perform, allows to isolate the different contribution (and weight in the global behavior) of each independent binding capability represented by each independent p-term in the sum.

Notice that the σ's acting on a single site could tend to keep it in the state -1 or $+1$ in accordance to their product. So, for example, for $p = 4$ one could have three sites, acting on the ith site, in a configuration, say $(+1, +1, -1)$, which favors the state $\sigma_i = -1$, even if in the whole there are more sites in the state $\sigma = +1$. The same local field is obtained when the configuration is $(-1, -1, -1)$, i.e., if all the three sites are empty. The energetic behavior of this extension is then deeply different from the previous case: Usually one deals with linear forces, which are generated

by quadratic potentials (i.e., $p = 2$) such that the Maxwell–Boltzmann probability distribution is Gaussian accordingly with what naively expected by a simple Central Limit Theorem argument and critical behavior, at $\alpha = 0$, arises to confirm this picture [20]. If a more complex scenario appears, then a violation of this linear framework is expected: for instance for $p = 3$ it is straightforward to check that even a positive J may have subtle anti-cooperation features: in fact, it is immediate to check that the energy would prefer the orientation of the spins $+1, +1, +1$ but also $+1, -1, -1$; this can be thought of as a competitive feature of the multi-attachment that naturally introduce negative cooperativity in the process under investigation.

Interestingly, this extension still shares with the simplest $p = 2$ case the same entropy: In fact, as in the two-body case, for this long-range interacting system the energy can be easily expressed as a function of the parameter θ describing the fraction of occupied sites, and of the concentration α

$$N^{-1}H_p(\theta, \alpha) = -\frac{J}{2}(2\theta - 1)^p - \frac{1}{2}\log(\alpha)(2\theta - 1). \quad (26)$$

while the entropy per site is exactly the same as in the $p = 2$ case. Given the effective free energy (still keeping $T = 1$ for the sake of simplicity)

$$F(\theta, J, \alpha) = \sup_{|\theta|}\left(-\frac{J}{2}(2\theta - 1)^p - \frac{1}{2}\log(\alpha)(2\theta - 1) - s(\theta)\right), \quad (27)$$

the minimum condition with respect to the order parameter θ reads off as

$$\theta(J, \alpha) - \frac{1}{2} = \frac{1}{2}\tanh\left(\frac{1}{2}pJ(2\theta - 1)^{p-1} + \frac{1}{2}\log(\alpha)\right). \quad (28)$$

This corresponds to the equilibrium state for the system, and the average fraction of occupied sites will be given by the solution of this equation. Once again, this equation, as in the $p = 2$ case, is strictly valid when the number of sites is large.

Again, we expect that for large interactions J (or chemical potentials) the energy term in (27) is the leading one, and the sites tend to be in the same state (this corresponds to a large magnetization), while for small values of the interaction strength the leading term is the entropic one, which prefers disordered states, i.e., states where the sites do not see each other.

5.1 Case $p = 3$

In this case the energy Eq. (26) is an odd function of $m = 2\theta - 1$ at fixed α

$$N^{-1}H_3(\theta, \alpha) = -J_3(2\theta - 1)^3/2 - \frac{1}{2}\log(\alpha)(2\theta - 1). \quad (29)$$

Its global minimum, corresponding to a fraction of occupied sites θ and satisfying

$$\theta = \frac{1}{2} + \frac{1}{2}\tanh\left(\frac{3}{2}J_3(2\theta - 1)^2 + \frac{1}{2}\log(\alpha)\right), \quad (30)$$

is located at an average number of occupied sites smaller than 1/2, when the concentration is very small. On the contrary, when the concentration is around $\alpha = 1$ (so that the chemical potential for binding is small) and $J_3 \gg 1$ the global minimum of energy corresponds to a large number of occupied sites. There is an intermediate region where $H_3(\theta, \alpha)$ can have two local minima for θ smaller and larger than 1/2, respectively, but the relative strength of the chemical potential $\log(\alpha)$ versus the interaction J_3 tells us which is the global one, corresponding to the equilibrium state. It is easy to see that the two minima (located, respectively, around $\theta = 1/4$ and $\theta = 1$) correspond to the same energy on the line $\alpha = \exp(-3 J_3/4)$, which this is the critical line where there is a two-phases coexistence in the limit of large J_3 or $\log(\alpha)$ and of negligible entropy contribution ($T \to 0$). However, the meaningful function to minimize is the whole free energy and in general one has to take into account the entropy term, which tends to favor an equal number of occupied or empty sites and to disfavor deviation from this (Fig. 3).

So we can identify three regions in the (J_3, α) plane: When J_3 is very small, the leading interaction is guided by the chemical potential $\log(\alpha)$, so that the sign of $\theta - 1/2$ is the same as the former and it vanishes for $\alpha = 1$. This corresponds to a weakly (W) cooperative system. Growing J_3, the system begins to feel mutual interactions, and the average number of occupied sites as a function of α has an inflection point for $\alpha^* > 1$, increasing quickly before that point and more slowly after (see for instance the case $J_3 = 0.8$ in Fig. 4). This is due to the interplay between entropy, which pulls the system toward $\theta = 1/2$, and the energy, which prefers $\theta = 0$ or $\theta = 1$ when the chemical potential is sufficiently large (Fig. 4).

As in the previous $p = 2$ case, we can perform a numerical study of the second derivative with respect to α of the binding isotherm, in order to discriminate between weak and strong cooperativity, to understand when an inflection point, and consequently a sigmoidal shape, appears: While for $p = 2$ we found that this happens for $J = 1/4$ in $\alpha = 0$ so that this exact value for J can be inferred by developing the second derivative for small values of α, here this is no longer true, as we find that the first inflection point is obtained for $J_3 = 0.5$, in correspondence of $\alpha = 1.5$. This is related to the fact that the minimum of the free energy passes quite abruptly
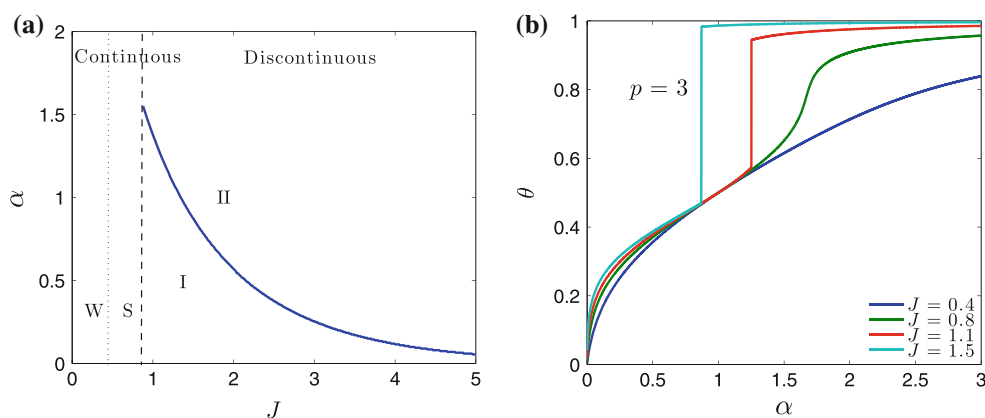
Fig. 3 Phases and binding isotherms for $p = 3$. **a** The figure shows the phases of a $p = 3$ system. For $J_3 < 0.50$ the system is weakly (W) cooperative, with no inflections; for $0.50 < J_3 < 0.86 = J_{3c}$ it is strongly (S) cooperative, having at least one inflection point; the *blue line* shows the J_3-dependent critical concentration at which, for $J_3 > J_{3c}$, a discontinuity in $\theta(\alpha)$ appears, passing from a relatively small θ(I) to a larger one (II) as the concentration increases (at fixed J_3). **b** Binding isotherms $\theta(\alpha)$ for different interaction strengths J_3. For

$J_3 = 0.4$ (*blue line*) the system is weakly cooperative, with a hyperbolic form; for $J_3 = 0.8$ (*green*) it has two inflections, the first for $\alpha = 1/2$ and the second for a larger α; for $J_3 = 1.1$ (*red*) the isotherm has a strong inflection for $\alpha < 1$ and a discontinuity for a value of the concentration between 1 and 1.5, corresponding to a transition to a more ordered state; for larger J_3, as the cyan curve for $J_3 = 1.5$ shows, the discontinuity is shifted toward $\alpha < 1$. Note that all the curves pass through the point (1, 1/2)
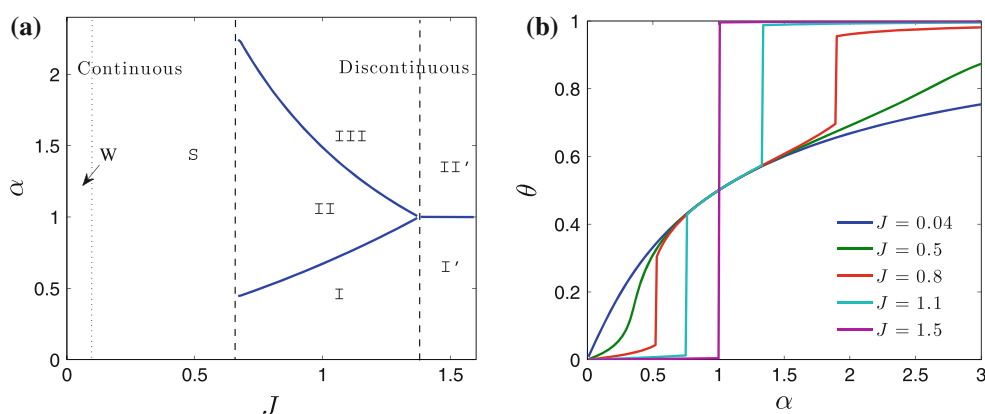

Fig. 4 Phases and binding isotherms for $p = 4$. **a** Phases for the $p = 4$ model. Binding is continuous for $J_4 < J_{c1} = 0.69$, and it passes from a weak (W) to a strong (S) continuous—regime at $J_4 = 1/24$; for $J_{c1} < J_4 < J_{c2} = 1.37$ isotherms have two discontinuities, one for a critical $\alpha_c < 1$ and the other one for a $\alpha'_c = 1/\alpha_c > 1$ (corresponding to a critical line, so that we can identify three (I, II, III) continuous regions at a fixed J_4; when $J_4 > J_{c2}$; however, there is only one large discontinuity at $\alpha = 1$, and the behavior is similar to the one observed in the $J_4 > 1$ phase for $p = 2$ (see Fig. 1). **b** binding isotherms $\theta(\alpha)$ of a four-bodies interacting system, for different values

of the interaction J_4. The binding isotherm for $J_4 = 0.04$ (the *blue line*) has no inflections and represents a practically non-cooperative system; when $J_4 = 0.5$ (*green*) the curve has an inflection point for a small concentration; for $J_4 > J_{c1}$ two inflection points appear and the isotherms develop two discontinuities corresponding, respectively, to the concentrations α_1 and α_2 such that $\alpha_1\alpha_2 = 1$, see the curves for $J_4 = 0.8$ (*red*) and $J_4 = 1.1$ (*cyan*); for interactions larger than J_{c2}, the system has just one discontinuity for $\alpha = 1$ and the binding isotherm tends to a step function, as for the purple line corresponding to $J_4 = 1.5$

(however, continuously and it is ultimately due to a violation of the quadratic shape for the energetic term) from values of θ not much larger than one half to larger values. We can then identify $J_3 = 0.5$ as the value separating a weak cooperativity regime from a strong cooperativity one. When J_3 is larger than this value, another zero in the second derivative appears, so that we have two inflection points. Above the critical value $J_3 = 0.9$, instead, we have a unique inflection point below $\alpha = 1$.

For a critical interaction strength of $J_3 = 0.86$, the system has a first-order transition so that θ is continuous in α below a critical concentration $\alpha^*(J_3) > 0$ and it grows abruptly above this threshold. Increasing J_3, this critical concentration becomes lower up to negative values at certain J_3. In this case, due to the strong interaction, a concentration smaller than $\alpha = 1$ in sufficient to have this discontinuous transition between a negative value of $\theta - 1/2$ and a positive one. When J_3, and so the cooperativity

is large, the critical line tends to be located at $\alpha = -\exp(3J_3/4)$.

5.2 Case $p = 4$

As for $p = 2$, in this case the energy is symmetric with respect to $\theta = 1/2$ when the concentration is equal to one, so that also the free energy features this symmetry

$$F(\theta, \alpha) = \sup_{|\theta|}\left(-2J_4(2\theta - 1)^4 - \frac{1}{2}\log(\alpha)(2\theta - 1) - s(\theta)\right) \tag{31}$$

and thermodynamic stability requires its minimization (w.r.t. θ) as

$$\theta = \frac{1}{2} + \frac{1}{2}\tanh\left(2J_4(2\theta - 1)^3 + \frac{1}{2}\log(\alpha)\right). \tag{32}$$

When the interaction among sites is small, again, we have a binding fraction ruled by the concentration of free ligands and vanishing as the latter goes to zero. For $J_4 = J_{c1} = 0.69$; however, the system has a first-order phase transition so that, coming from small concentrations, there is a value $\alpha_c(J_4) < 1$ for which θ changes abruptly to a larger value, which is smaller than 1/2. Then, $\theta(\alpha)$ varies continuously in the interval $\alpha_c(J_4) < \alpha < \alpha_c(J_4)'$, passing through the point $(1, 1/2)$, and there is a new transition with a discontinuity at an inverse value of $\alpha_c(J_4)$, $\alpha_c(J_4)' = \alpha_c(J_4)^{-1}$. In fact, for this range of interaction strengths J_4, and for concentrations around $\alpha_c(J_4)$, the free energy has two local minima coming from the well-matched competition between the energetic and the entropic terms, the former preferring small, "ordered" θ, while the latter has always its maximum at $\theta = 1/2$. The concentration tells us which is the global minimum and the two minima are equal at α_c. The same happens around the symmetrical value $\alpha_c(J_4)'$.

The critical concentration α_c tends to one with the interaction strength growing, and for $J_4 = J_{c2} = 1.37$ the system becomes ferromagnetic. In this case the mutual interaction is the overwhelming force driving the system, and, as in the previous $p = 2$ case, the binding isotherm has a discontinuity when passing from $\alpha < 1$ to $\alpha > 1$, changing abruptly from a large negative value (depending on J_4) to a positive, opposite value (see Fig. 4). It is interesting to note that the values of α_c and α_c' depend on J_4 and even for $p = 3$ we find a critical concentration depending on J_3: because this dependence is absent in the $p = 2$ case, an experimental J_4-dependent critical concentration may indicate that a multiple interaction effect is acting (this can be seen for example in [23]).

Analogously to the cases $p = 2,3$, we can determine exactly the value $J_4 = 1/24$ as the one for which a first

inflection point appears, so that the binding isotherm passes from a weak to a strong cooperativity region. In fact, as for the $p = 2$ case (see Eq. 20) by gaining the second derivative of the binding isotherm for small α one can see that the leading term is proportional to $(1 - 24J_4)$. The isotherm has a unique inflection point until $J_4 = 0.45$, then a second point appears at $\alpha = 2.4$, which for larger J_4 splits in two points, so that for $0.45 < J_4 < J_{c1}$ we have three inflections. The ones corresponding to the smaller and to the larger values of α disappear when J_{c1} is reached and, instead of these inflections, the isotherm has two discontinuities.

A discontinuous behavior which could be explained in term of two and multisite interactions between hosting sites has been observed in the binding isotherm of long chain alkyl sulfates and sulfonates to the protein bovine serum albumin, and in the adsorption isotherm of alkylammonium chlorides chains on the biotite surface [26]. Typically, if there are multi-site interactions (with $p > 2$) it is very likely that also two-bodies interactions are present, and one should consider the several possible interactions with different strengths J_p in the energy term, while for the sake of clearness we considered them separately.

Before concluding some remarks are in order. As we have shown, the phenomenology pertaining to systems with p-body interactions depends sensitively on p and this allows to infer information about the properties of the system under study, starting from its reaction rate. On the other hand, we also notice that when looking at the most likely configuration, that is the most likely value of θ for a given parameter set (p, J, α), we find that it exists and it is unique: if we, for the sake of simplicity, focus just on even $p > 2$ values, we can see that the amount of solutions is constant, namely, independent by the amount and complexity of the cooperating/anti-cooperating binding sites. More precisely, the self-consistent relation in Eq. 28 may allow for one or two distinct solutions, but only one is a global minimum for the free energy: the minima of the free energy do not scale, but simply shift, with p, while the global minimum is always unique. This argument may be applied to the problem concerning the folding of (long) proteins, whose secondary and tertiary structure is essentially always the same, despite a large number of multi-attachment is in principle possible [27].

6 Conclusions and perspectives

In this paper we pursued the strand early paved by Thompson [7] in modeling chemical kinetics with statistical mechanics techniques: highlighting the emergent properties in this field, namely cooperation among binding sites, we relaxed the original assumption of dealing with

geometric models (i.e., linear chains) in favor of mean-field models as the latter may properly account also other experimental findings (as discontinuous jumps or folding) and benefit of a broad tunable set of scenarios.

After a streamlined introduction to the modern definitions of "cooperativity" in chemical kinetics, we developed a one-to-one mapping between chemical variables (binding sites, substrate, etc) and the statistical mechanics counterparts. Then, we applied statistical mechanics prescriptions, based on the variational principles, and we found an expression for the reaction rate θ (representing the number of occupied sites) as a function of the substrate concentration α. In doing so the interaction constant J between binding sites is treated as a free (microscopic) parameter. We show that by tuning J we are able to recover a plethora of different behaviors, ranging from non-cooperative ($J = 0$), weak cooperativity ($J < 1/4$), and strong cooperativity ($J > 1/4$). Our results are also shown to be consistent with the number of definitions of cooperativity (e.g., Hill, Koshland, or range), previously introduced. Furthermore, we found a universal criterion to distinguish between weak and strong cooperativity, that is, by looking at the inflections of the second derivative of the free energy. Indeed, we found that the existence of cooperativity (i.e., a positive interaction constant) is not sufficient for the existence of a flex in the reaction rate. Otherwise stated, a non-sigmoidal law does not necessarily mean that no cooperativity is at work. Such situations are here referred to as cooperativity of weak degree.

There are several directions along which this work can be extended: for example including a well-defined topology for binding sites [28], which would account to more realistic interaction scalings among the binding sites. Also, non-strictly-positive couplings would realize a spin-glass system which, as well known from statistical mechanics, significantly enriches the phenomenology, to be possibly mapped in terms of reaction kinetics.

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